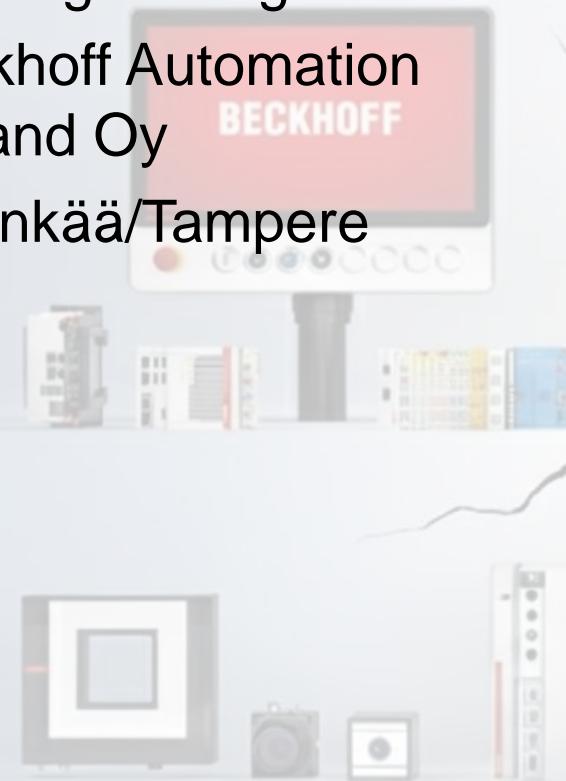


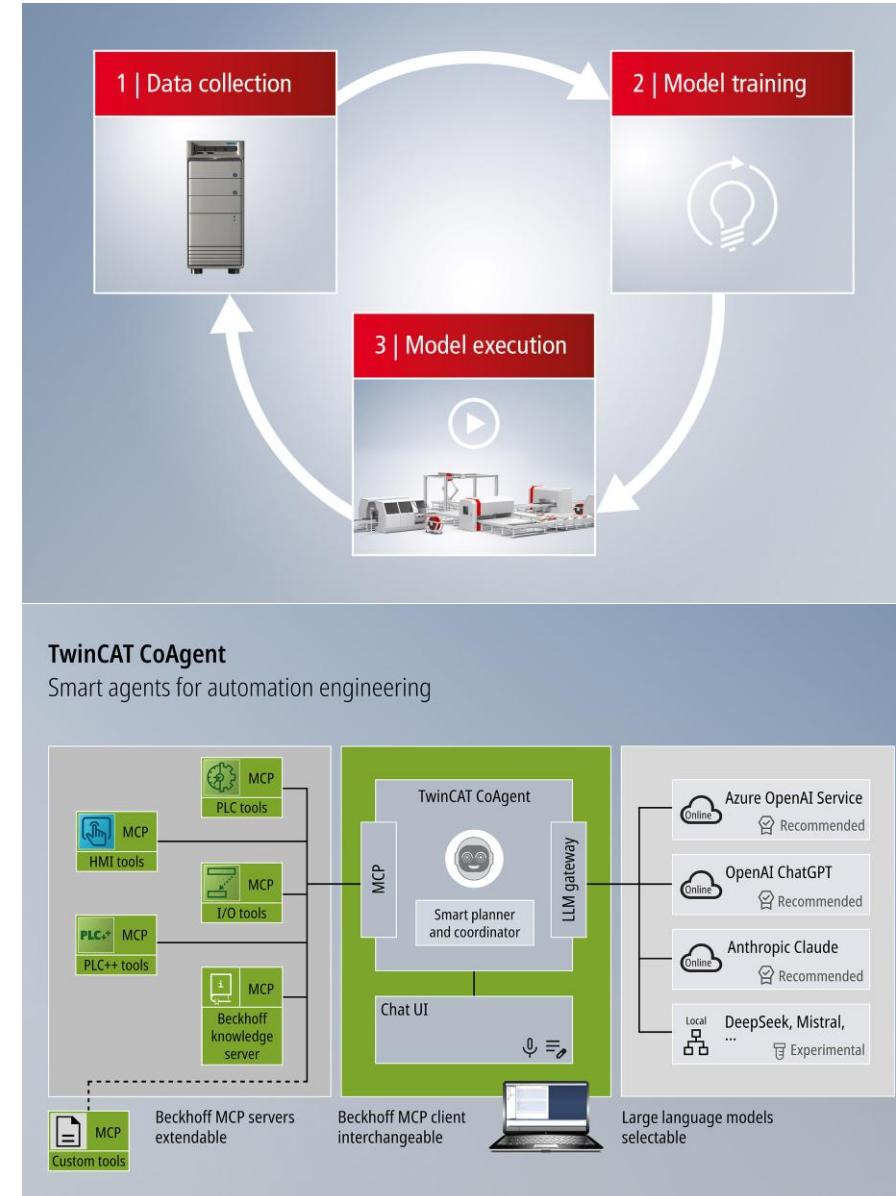


- Janne Kauppila
- Training Manager
- Beckhoff Automation
Finland Oy
- Hyvinkää/Tampere



Tekoäly automaatiossa
AIK 

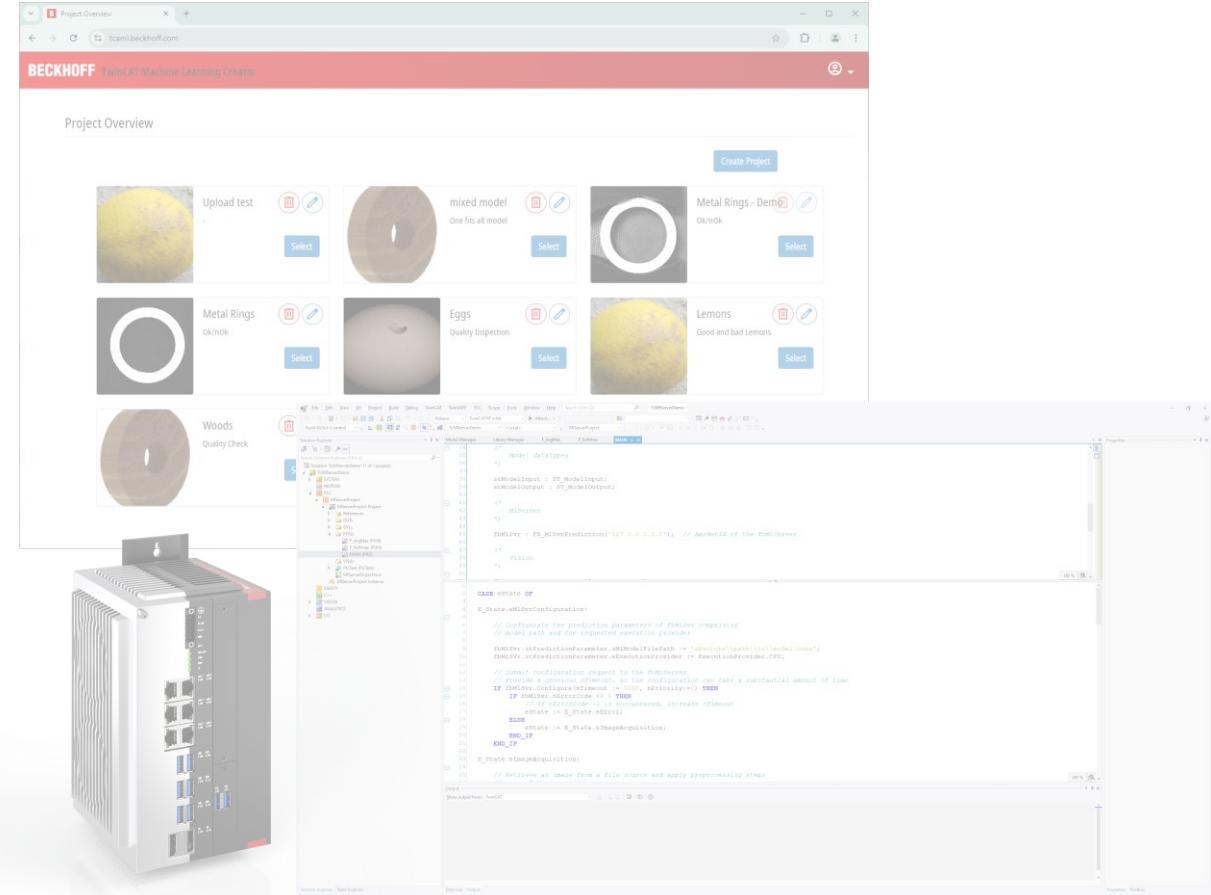
- TwinCAT Machine Learning
 - Seamless integration of AI at the control level
 - AI models running directly on the PLC
 - Continuous workflow from data acquisition to real-time execution
- TwinCAT CoAgent
 - AI-assistant for engineering and operation
 - Combines the latest generative AI models with specialized AI agents
 - Model Context Protocol (MCP) for open and seamless integration



Part I: Applications



Part II: Technologies and Tools



Overview on possible AI-applications in industrial Automation

BECKHOFF

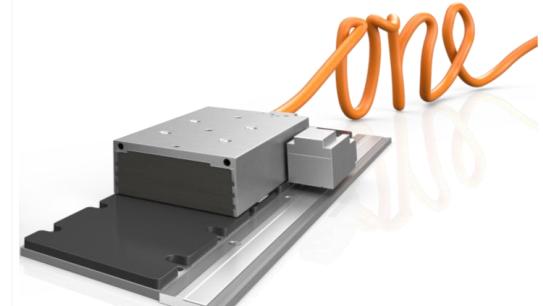
Collaborative and context-aware robotics



Rejects reduction



Machine optimization



Integrated quality inspection

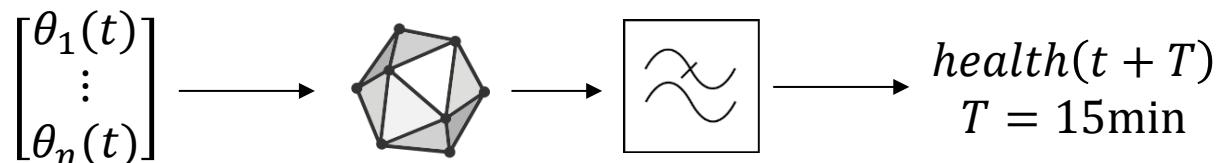
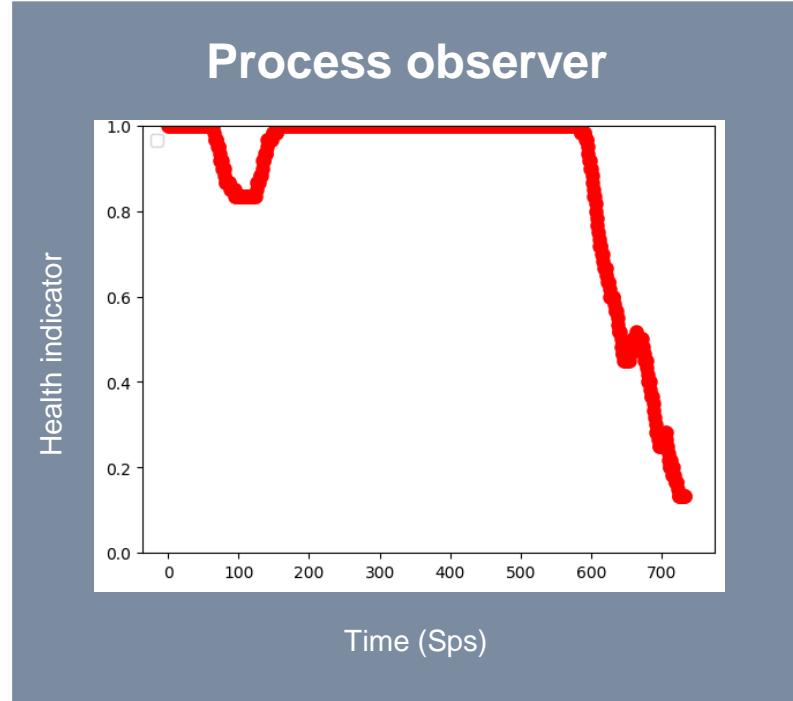
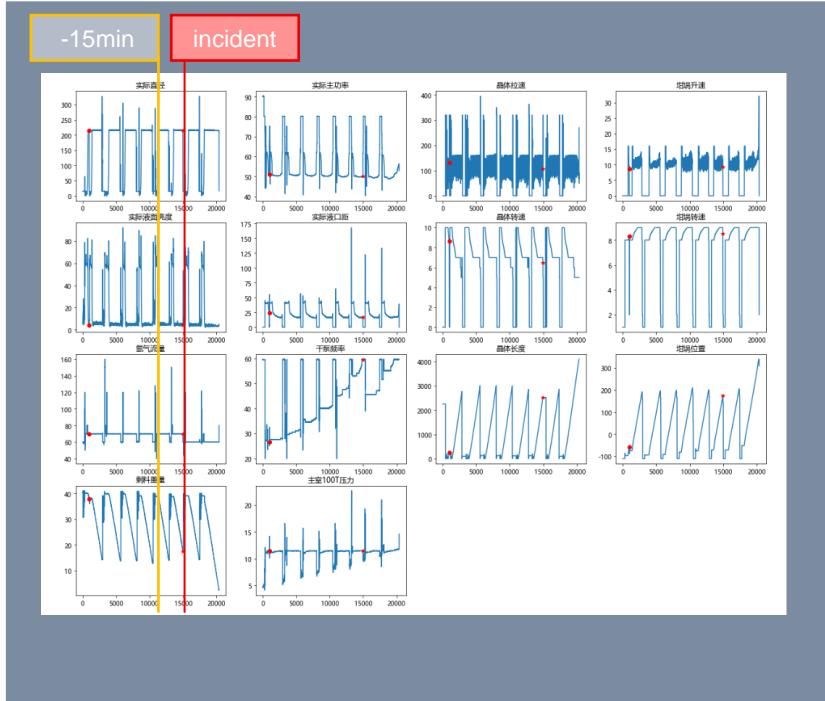


Predictive maintenance



Reduction of production waste AI model as process observer

BECKHOFF

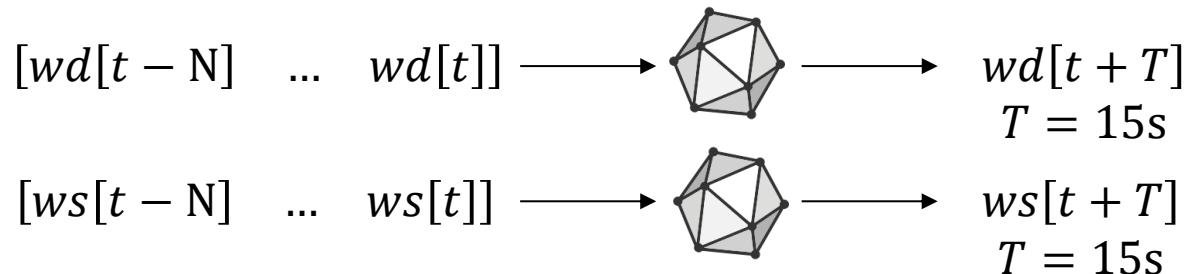
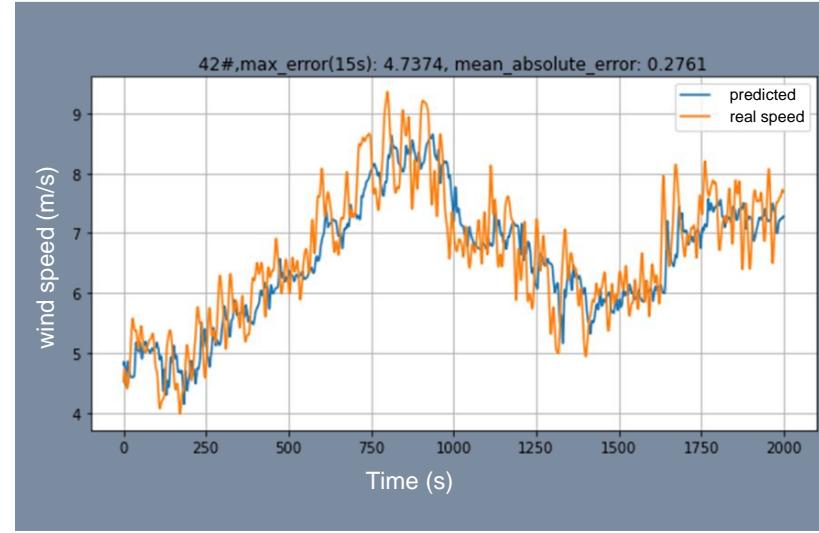
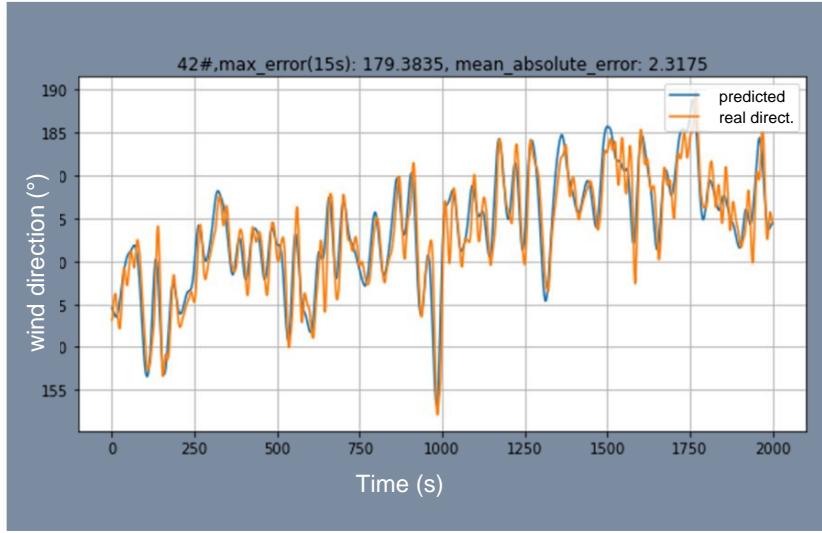


- crystal growth takes more than 24h, process especially critical in the last hours
- AI model trained on historic data to predict possible process problems 15min in advance

Machine optimization

Prediction of wind speed and direction

BECKHOFF



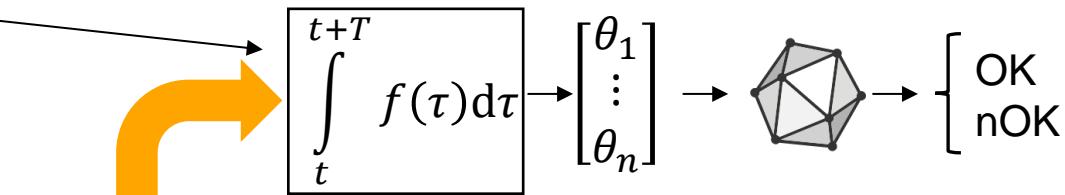
- Prediction of wind speed (ws) and direction (wd) 15 seconds into the future, based on a N seconds time window of the past
- Goal: predictive control of pitch and yaw

Control-integrated quality inspection

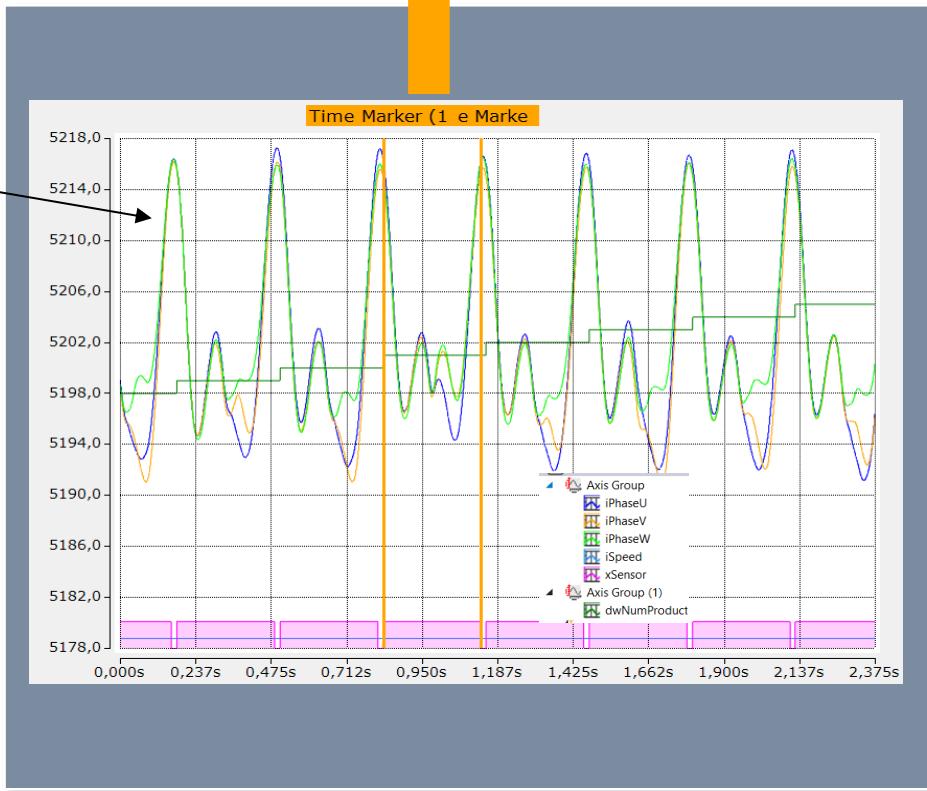
Testing of packaging in the food industry

BECKHOFF

Create signal features,
e.g. mean, std, ... within
time interval



current feedback
of servo motor



- Detect faults in the final packaging process of instant noodles based on motor currents
- Cutting and sealing process observation
- Feature generation with TwinCAT Condition Monitoring library
- Anomaly detection model trained to detect defects



© AdobeStock (ThamKC)

Control-integrated visual inspection

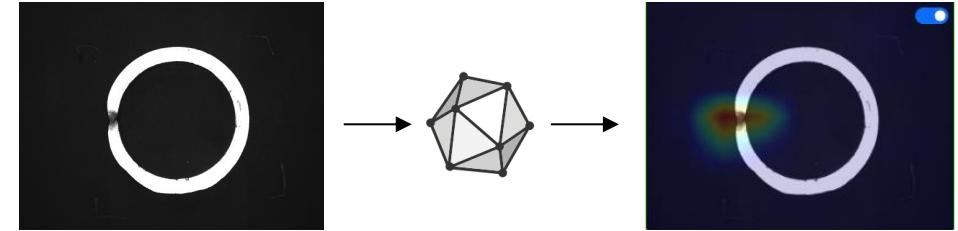
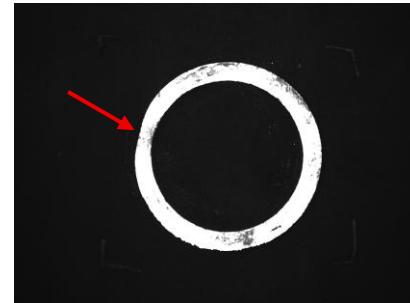
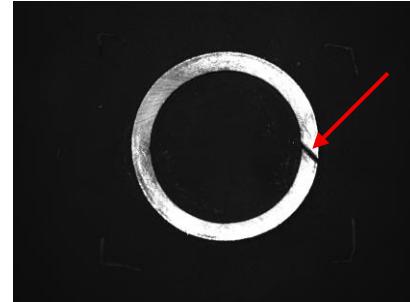
Testing of metal rings

BECKHOFF

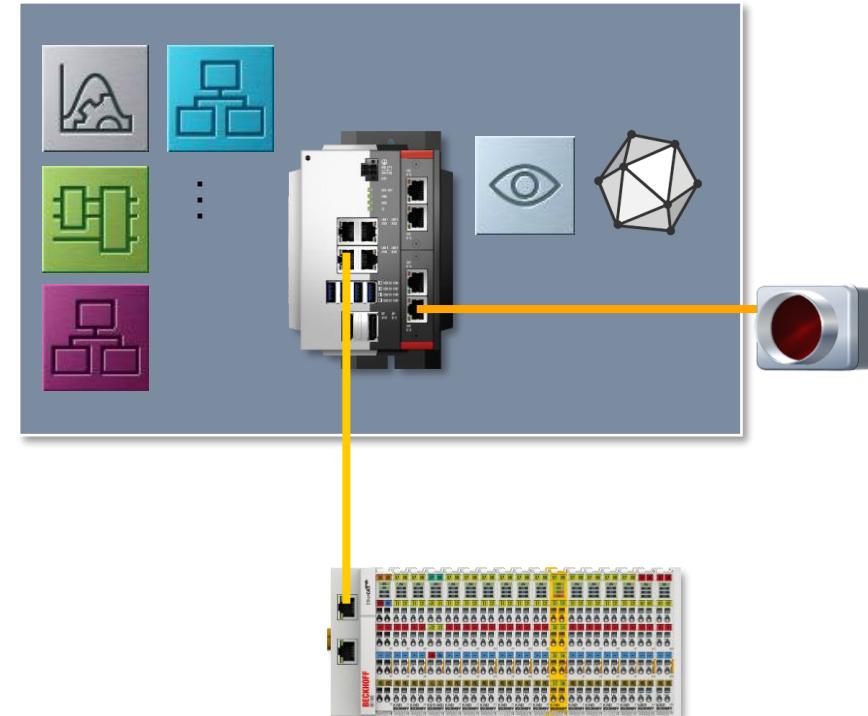
Ok



nOk



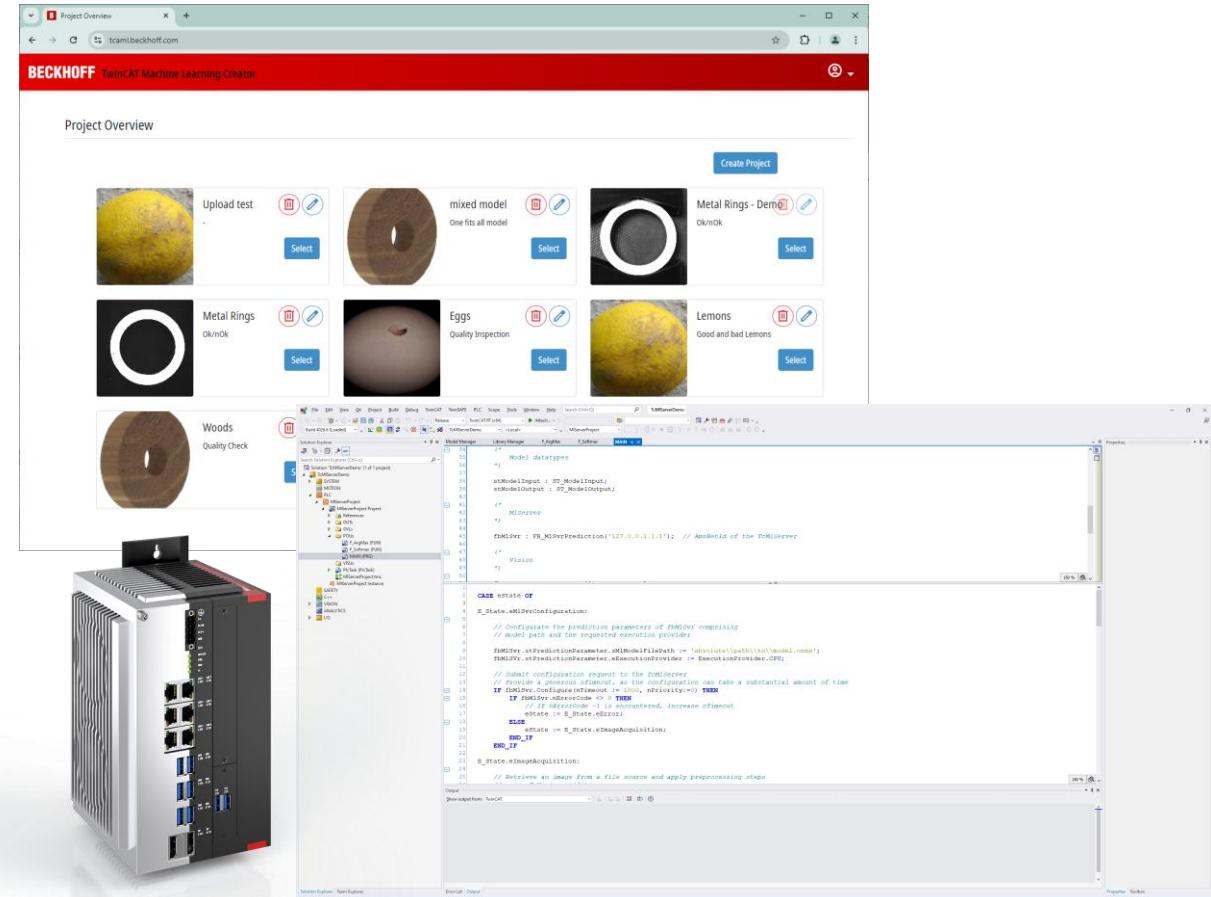
control system with vision and AI



Part I: Applications

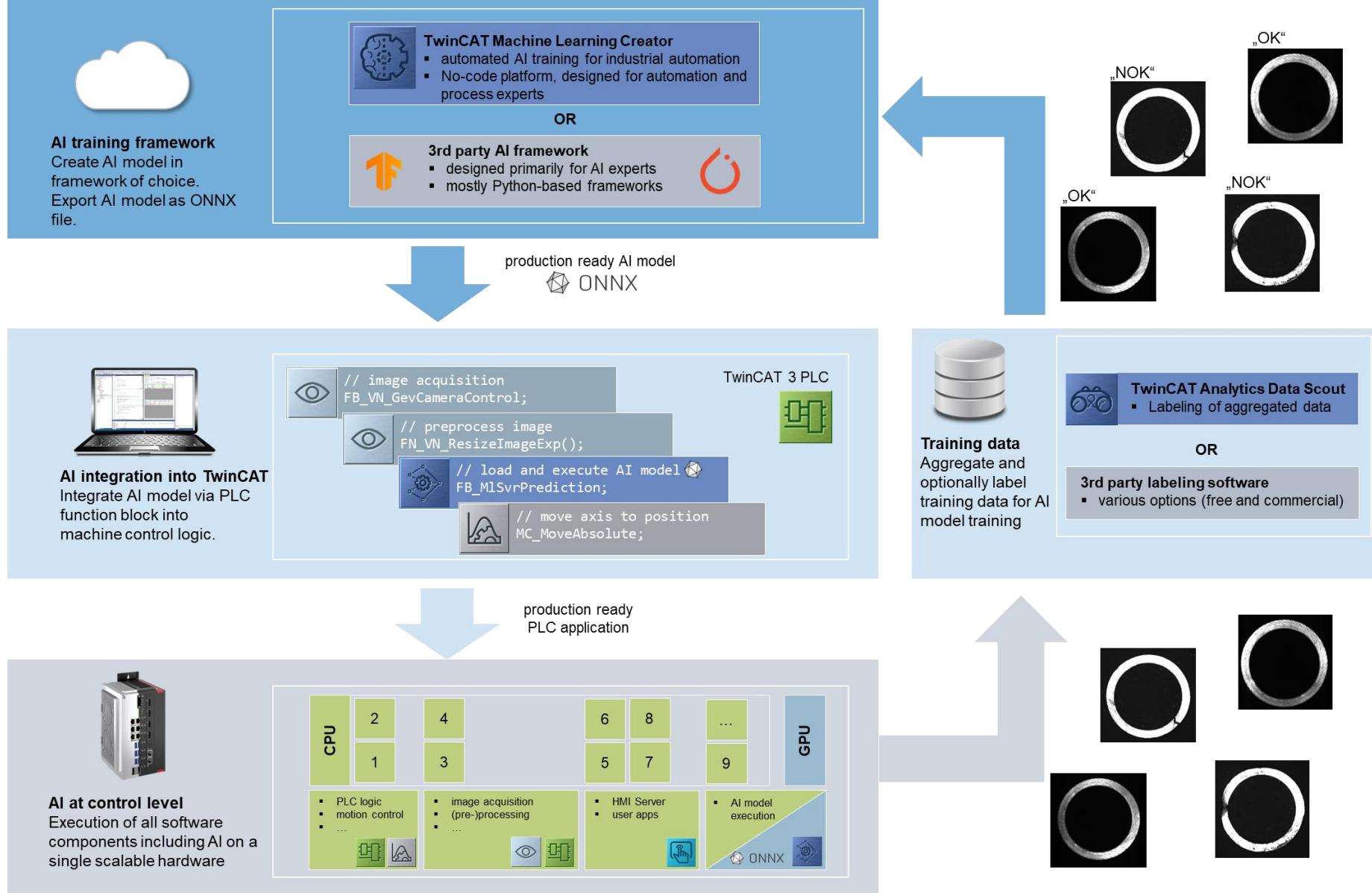


Part II: Technologies and Tools



AI Model Lifecycle: Training, Integration und Deployment

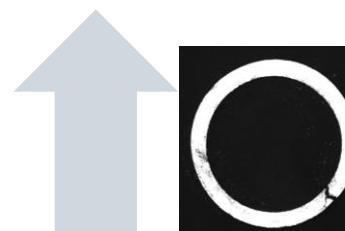
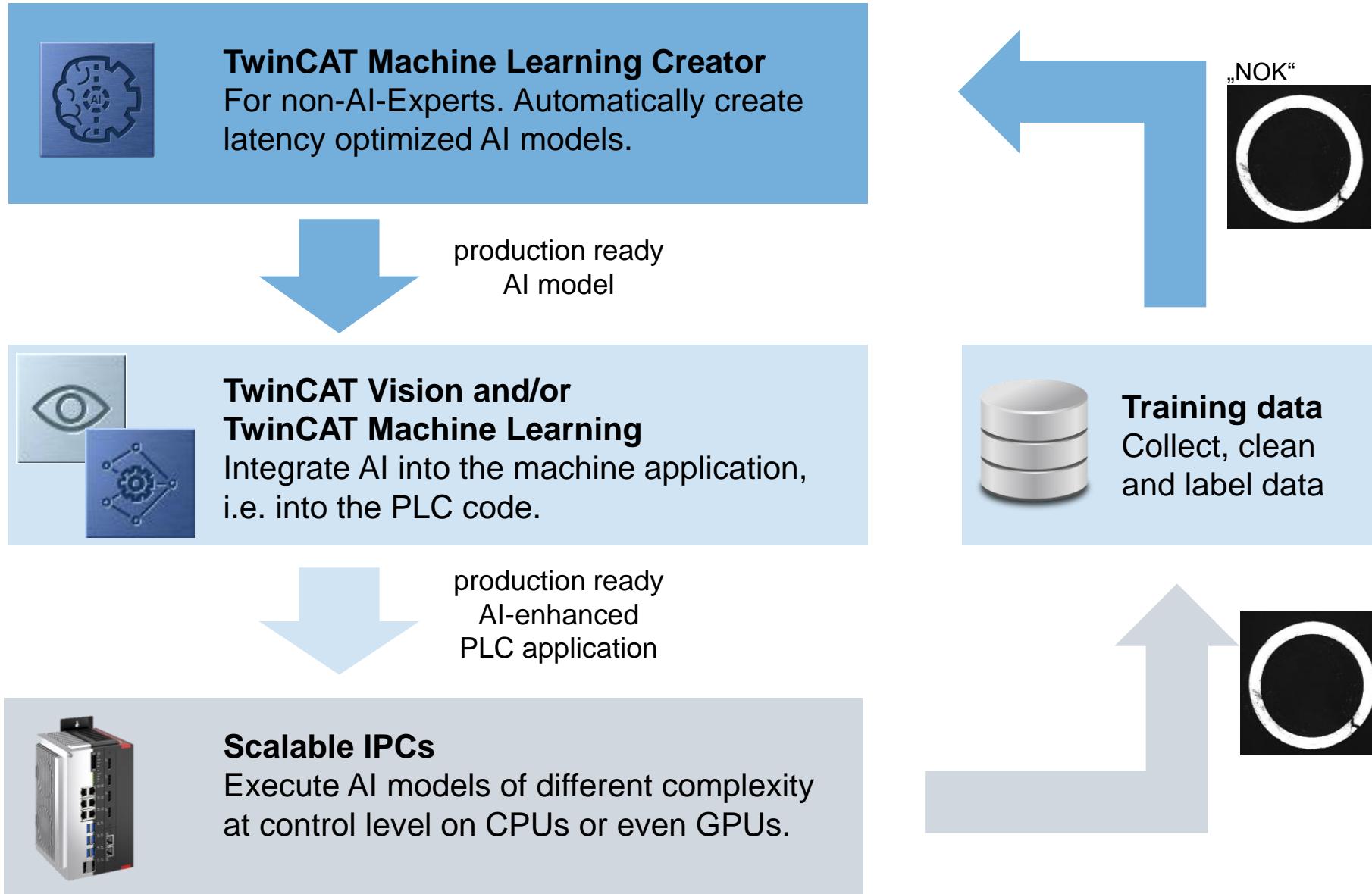
BECKHOFF



The Beckhoff AI ecosystem

Complete workflow for integrating AI at control level

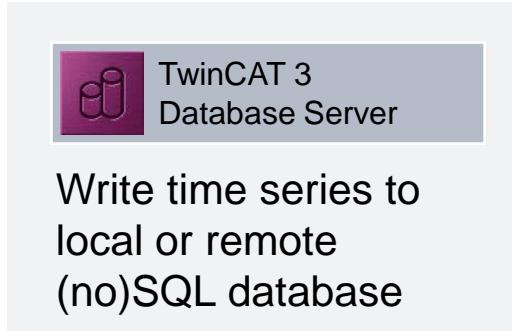
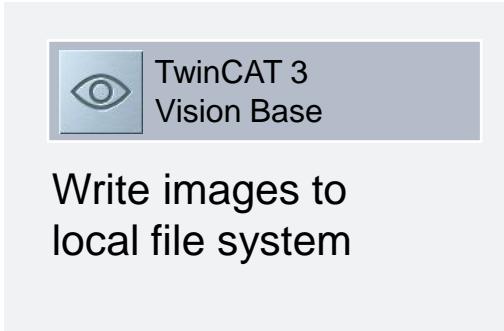
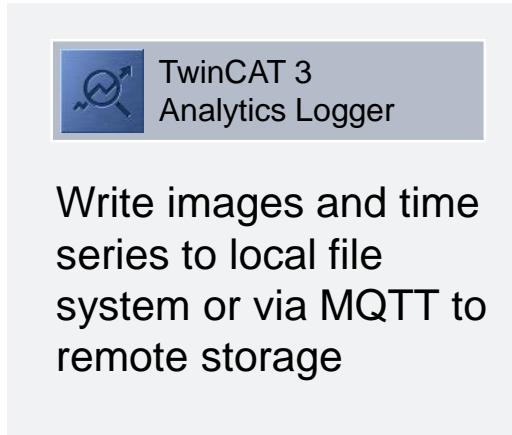
BECKHOFF



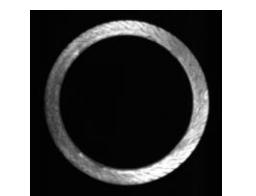
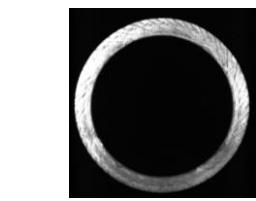
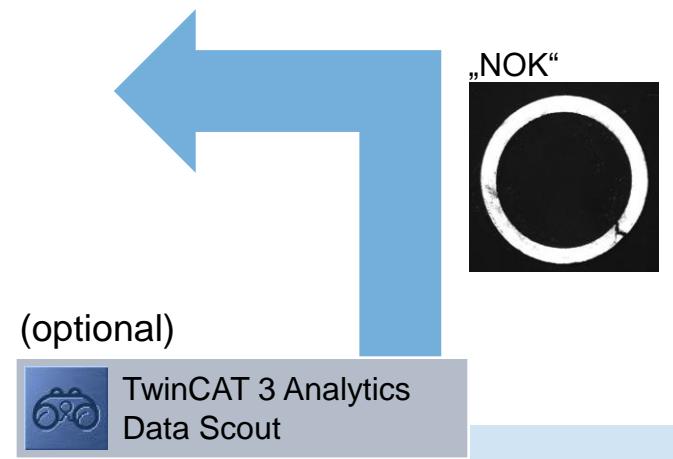
The Beckhoff AI ecosystem

Collect, clean and label data

BECKHOFF



Scalable IPCs
Data logging realized in software modules.
Logging performance depends on IPC and network capacity as well as software.



TwinCAT Machine Learning Creator

AI model training for domain experts in automation

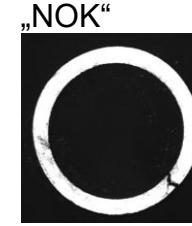
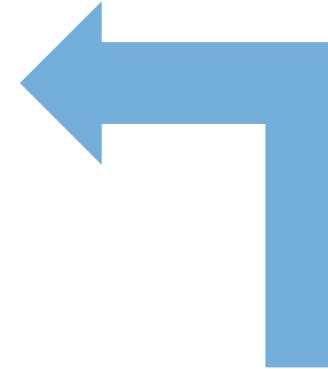
BECKHOFF



TwinCAT Machine Learning Creator
For non-AI-Experts. Automatically create
latency optimized AI models.

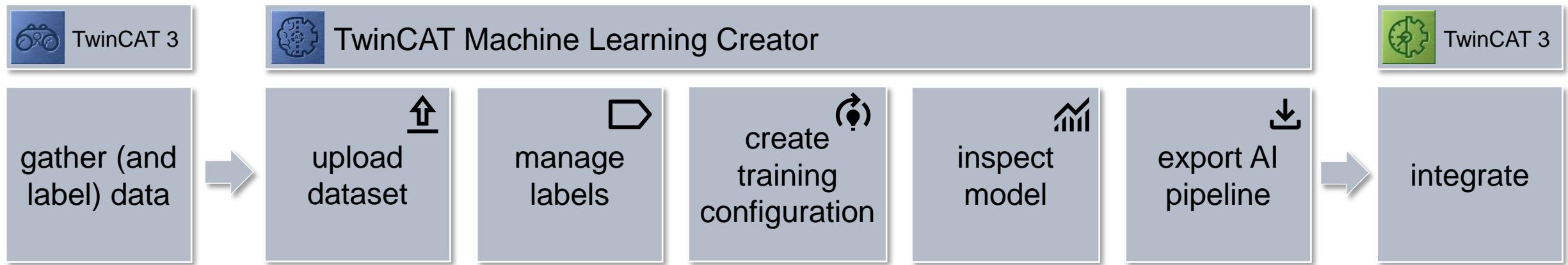


production ready
AI model



TwinCAT Machine Learning Creator Workflow

BECKHOFF



TwinCAT Machine Learning Creator

Benefits

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Benefits for domain experts:

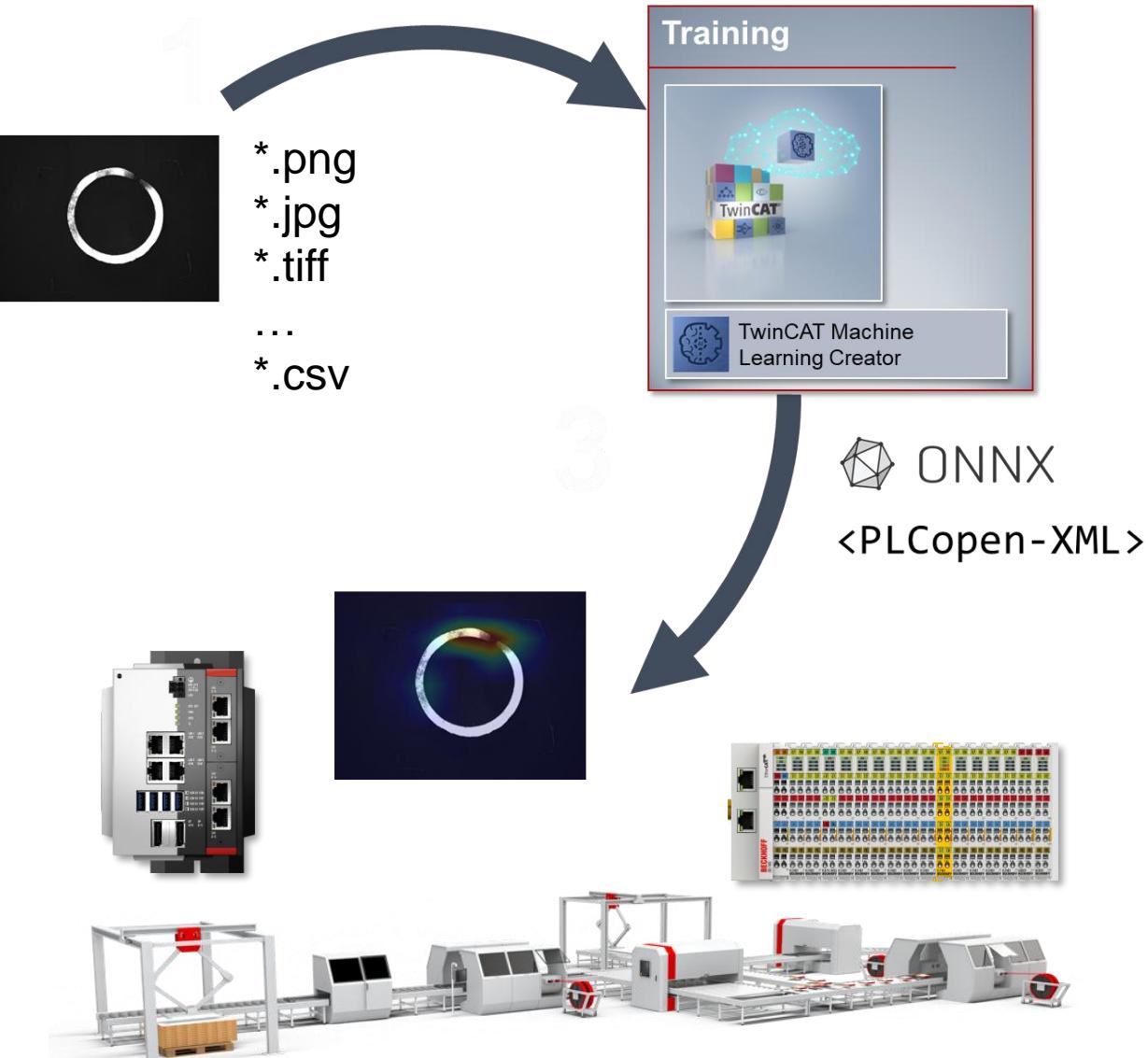
- democratization of ML: accessibility of state-of-the-art ML methods
- designed for people who are not AI experts
- standardization of ML training processes
- user-aware no-code platform

Benefits for AI experts:

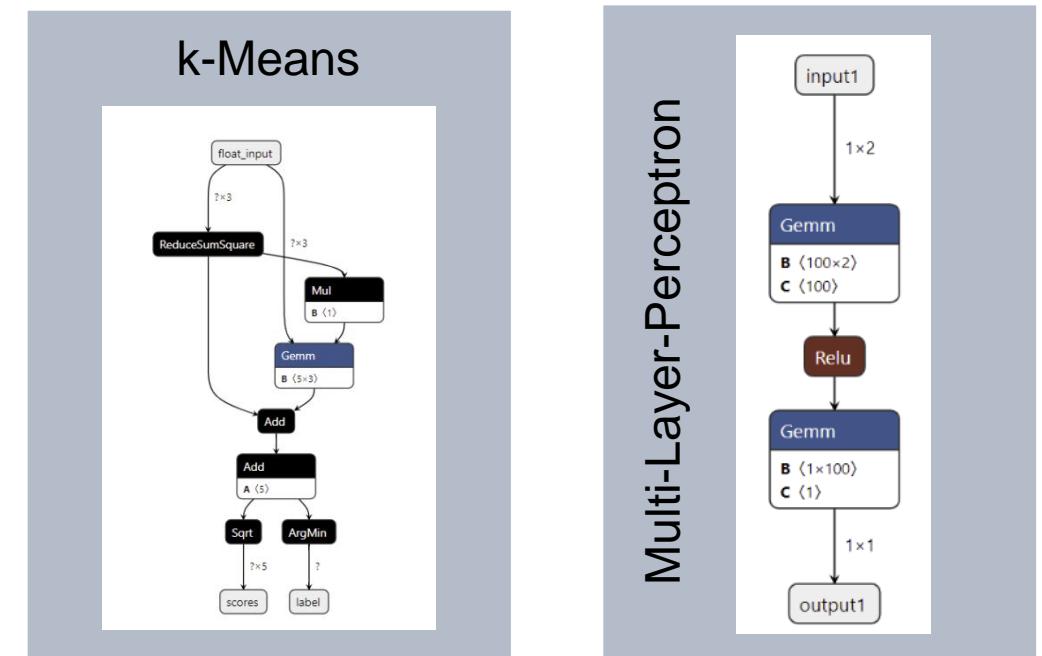
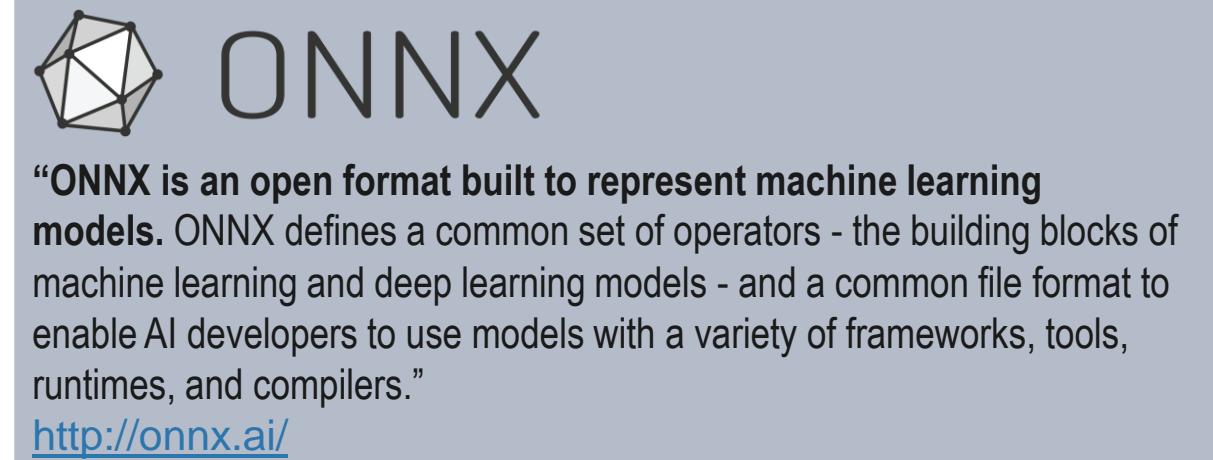
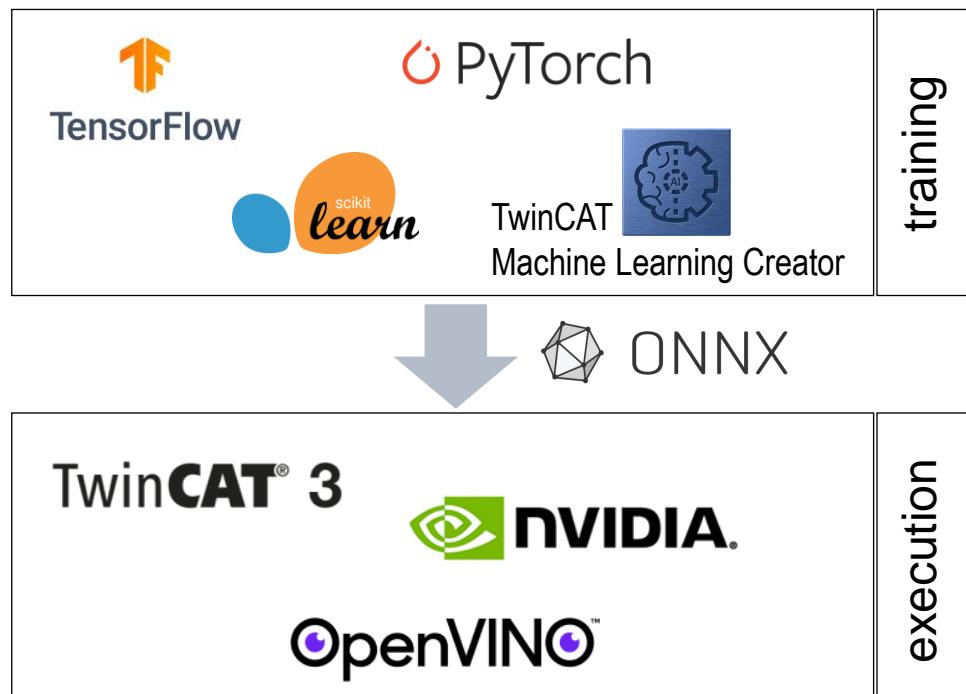
- efficiency: acceleration of training processes
- inspiration: version zero generator

Industrial automation focus:

- latency optimized, hardware-aware AI models
- export PLC code for easy integration into automation system



- **Open Neural Network Exchange**
- open format representing (trained) AI-models
- interoperability between AI training frameworks and AI inference engines



TwinCAT Machine Learning Creator Roadmap

BECKHOFF

Computer Vision

Image Classification

Task: Classify the image

Beta Phase: Started

Planned Release: Q1/2026



Anomaly Detection

Task: Locate anomalies

Beta Phase: Q1/2026

Planned Release: Q3/2026

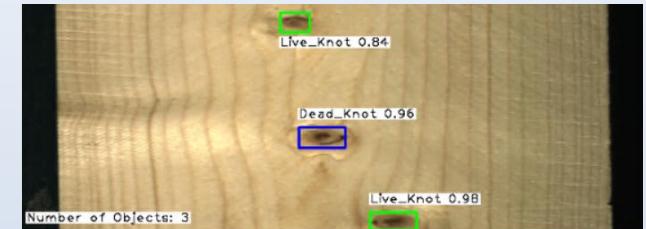


Object Detection

Task: Locate and classify objects

Beta Phase: Q3/2026

Planned Release: Q4/2026

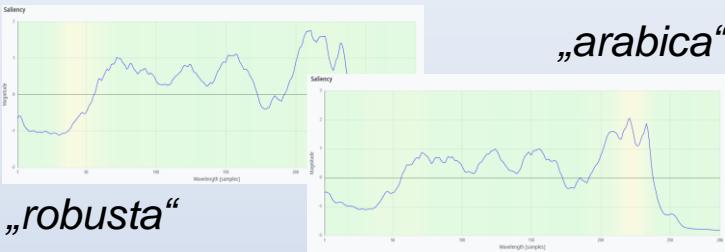


Signal Classification

Task: Classify signals

Beta Phase: End of 2026

Planned Release: tbd



Signal Anomaly Detection

Task: Locate anomalies

Beta Phase: tbd

Planned Release: tbd

Time Series Forecasting

Task: Forecast future values

Beta Phase: tbd

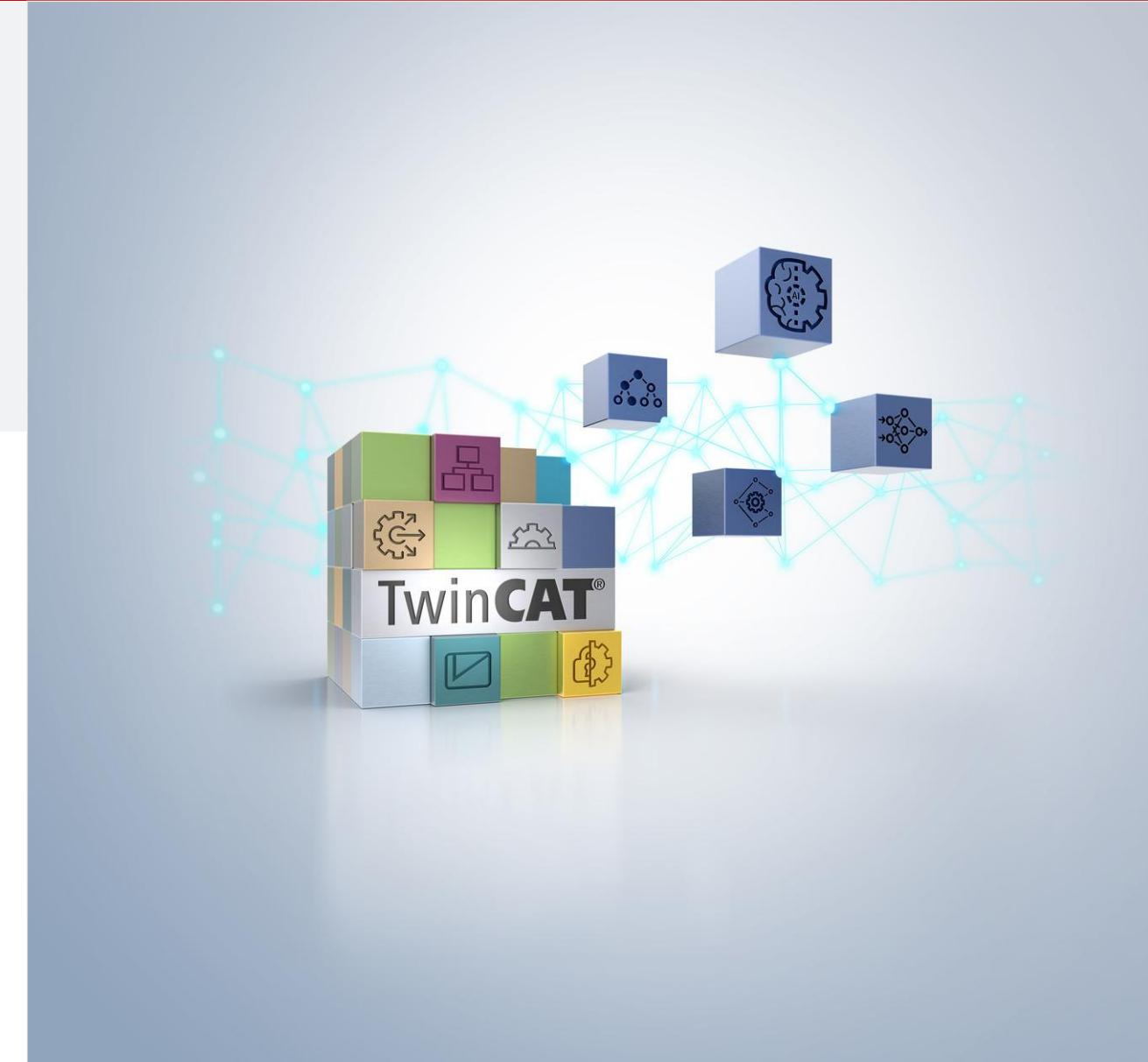
Planned Release: tbd

Upcoming

“With *Signals & Time Series*, the TwinCAT Machine Learning Creator becomes the universal AI tool for every machine – visual or signal-based.”

Automated AI Model Creation for Signal and Time Series Data

- Extension of the TwinCAT Machine Learning Creator
- Same easy to use workflow like with vision data



Customer Benefits

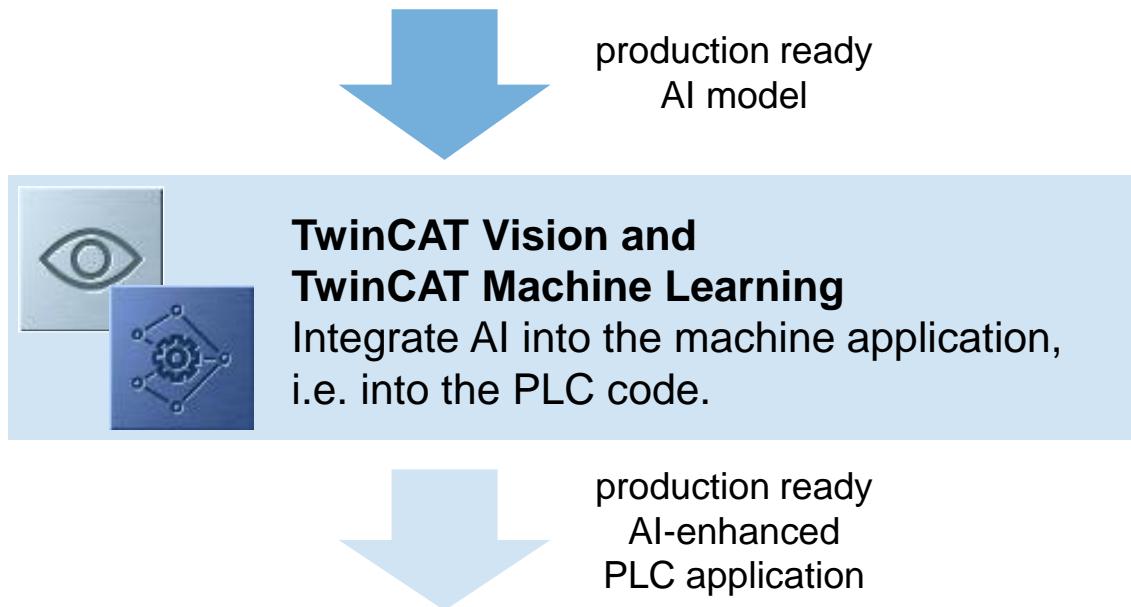
- Unlocks AI potential for any machine, even without camera systems
- Provides an easy and low-effort entry point into AI-enhanced automation, delivering fast value and scalable results

Typical Applications

- Anomaly detection & predictive maintenance
- Process monitoring and quality assurance (e.g., welding, pressing, packaging)
- Tool wear detection from current, vibration, or acoustic data



- **democratization**
 - empowers automation engineers to create task-specific AI models
- **accuracy**
 - creates the most effective solution for a customer-specific task
- **efficiency**
 - creates solutions more than 10 x faster compared to hand-crafted AI models
- **scalability**
 - no own infrastructure needed, uses scalable AWS resources
- **standardization**
 - structured and well-documented AI model training simplifies reviewing processes



AI at control level

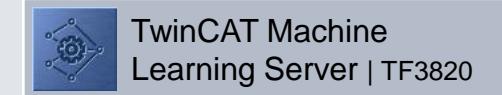
Products and features

BECKHOFF

Products



small and latency critical AI models

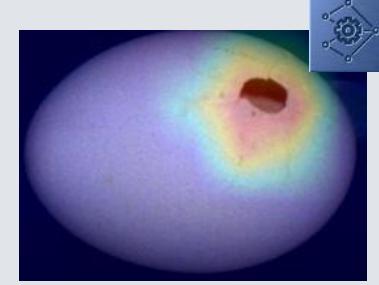
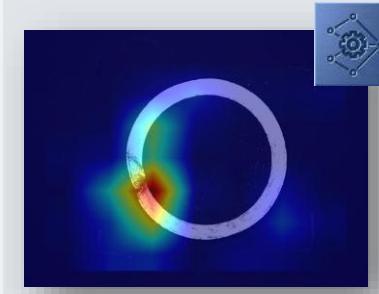


TwinCAT Machine Learning Server | TF3820

medium to large AI models

Features

| Deterministic AI | Accelerated AI-Server |
|---|---|
| deterministic execution in TwinCAT-runtime | Near-real time execution (in separate process) |
| Execution on standard x64 CPUs | Acceleration possible with NVIDIA GPUs |
| supports selected AI models and operators | supports recent ONNX operators |
| Licence-Bundle | Can also be used as a server in a network with several clients |
| Standard PLC Function block for simple integration into TwinCAT PLC | |
| Interoperability through ONNX support | |
| Update AI-model at runtime without new compile or TwinCAT Stop | |



Deterministic AI

deterministic execution in TwinCAT-runtime

Execution on standard x64 **CPUs**

supports **selected AI models** and operators

Licence-Bundle

Accelerated AI-Server

Near-real time execution (in **separate process**)

Acceleration possible with NVIDIA **GPUs**

supports **recent ONNX operators**

Can also be used as a **server** in a network with several clients

Standard PLC Function block for simple integration into TwinCAT PLC

Interoperability through ONNX support

Update AI-model at runtime without new compile or TwinCAT Stop

TF3800 | TwinCAT Machine Learning Inference Engine

Key Facts

BECKHOFF

AI models

- Classic machine learning models
- ONNX support
- Trained offline e.g. using Python, R or others

Execution details

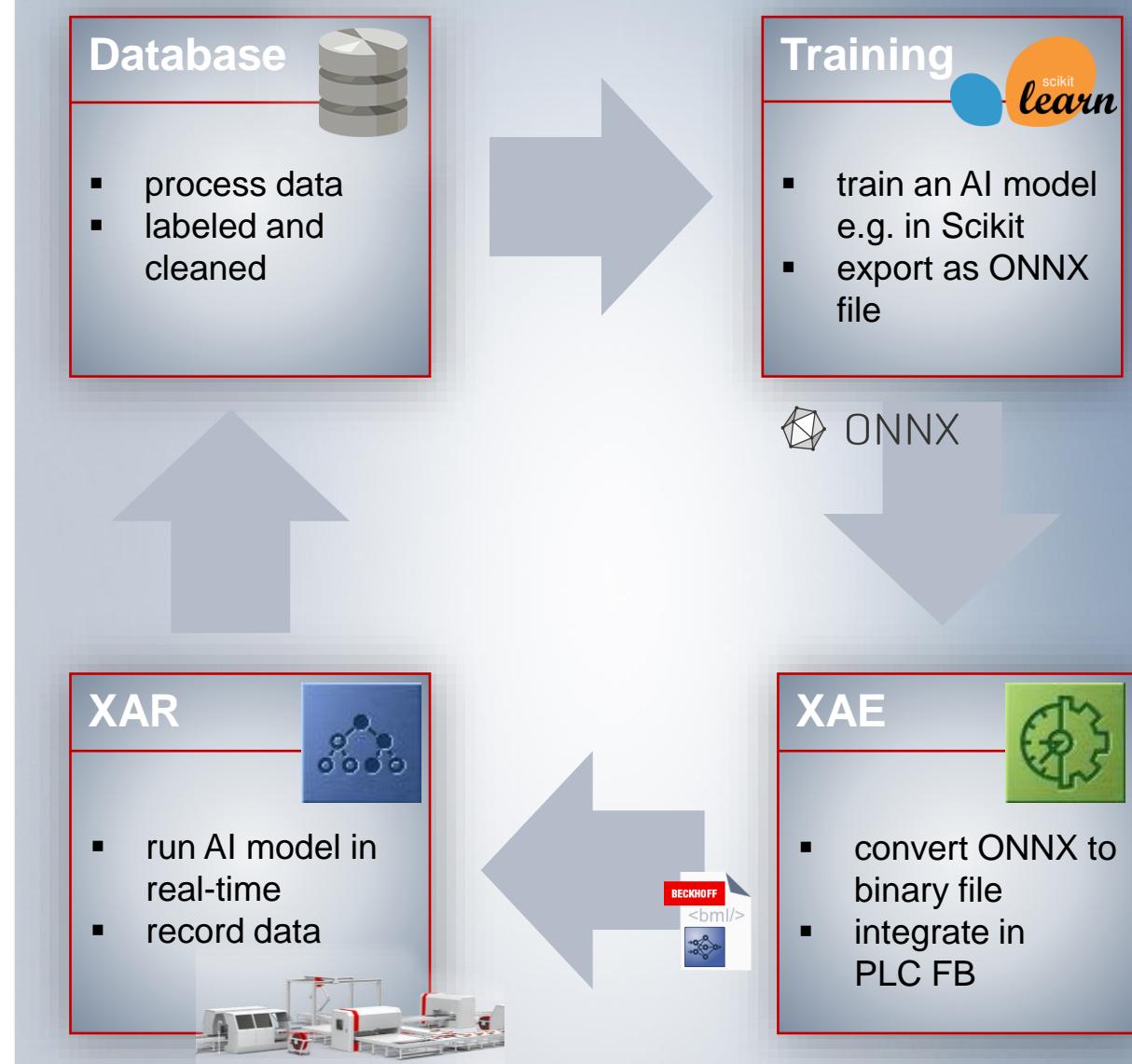
- CPU
- single core
- deterministic real-time

Interface

-  FB_M11Prediction
-  Configure
-  Predict

Supported models

- SVM
- k-means
- PCA
- Random Forest
- Decision Trees
- Gradient Boosting
- XGBoost
- LightGBM
- ExtraTree(s)



TF3810 | TwinCAT Neural Network Inference Engine

Key Facts

BECKHOFF

AI models

- Models of type Neural Network
- ONNX support
- Trained offline e.g. using Python, R or others

Execution details

- CPU
- single and multicore (model specific)
- deterministic real-time

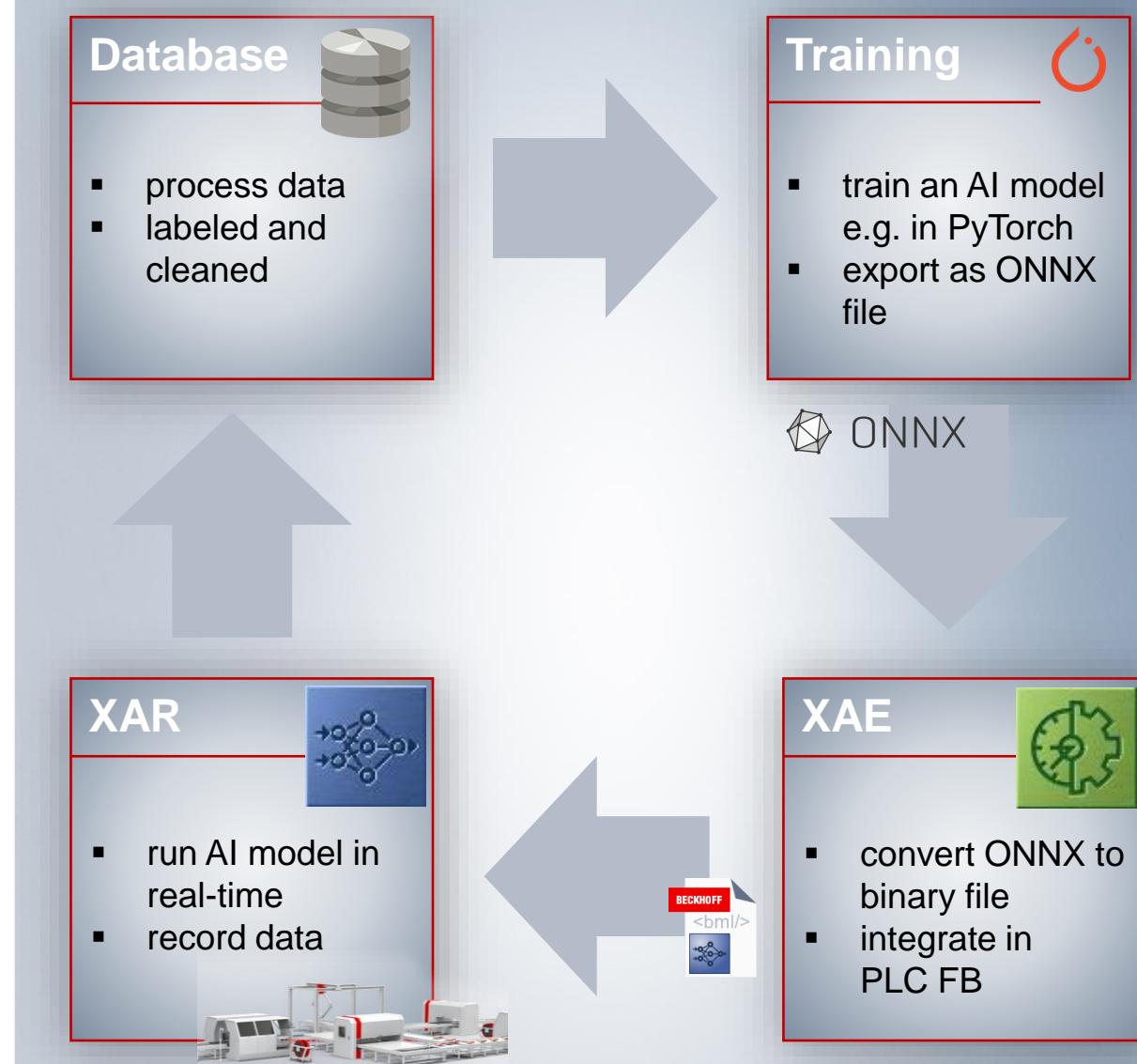
Interface

- FB_M11Prediction*
- Configure
- Predict

Supported models

- MLP
- LSTM
- CNN

*may change in newer release



AI models

- Models of type Neural Network
- ONNX support
- Trained offline e.g. using relevant Python Frameworks or TwinCAT Machine Learning Creator

Execution details

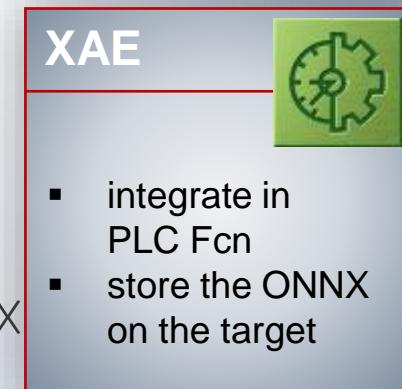
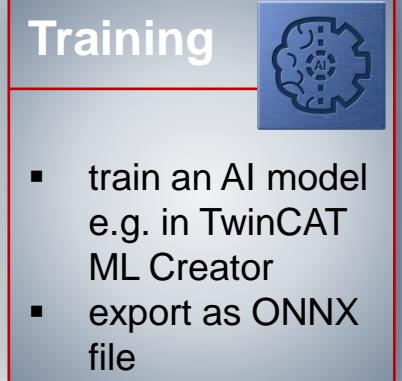
- CPU
- single and multicore (model specific)
- deterministic real-time

Interface

```
hr := F_VN_ExecuteNeuralNetwork(  
    ipNN      := ipModel,  
    ipSrcImage := ipImage,  
    ipDestImage := ipResult,  
    hrPrev    := hr);
```

Supported models

- MLP
- CNN



AI models

- Supports everything that can be represented as ONNX model
- General ONNX Opset version 21 support
- Trained offline e.g. using relevant Python Frameworks or TwinCAT Machine Learning Creator

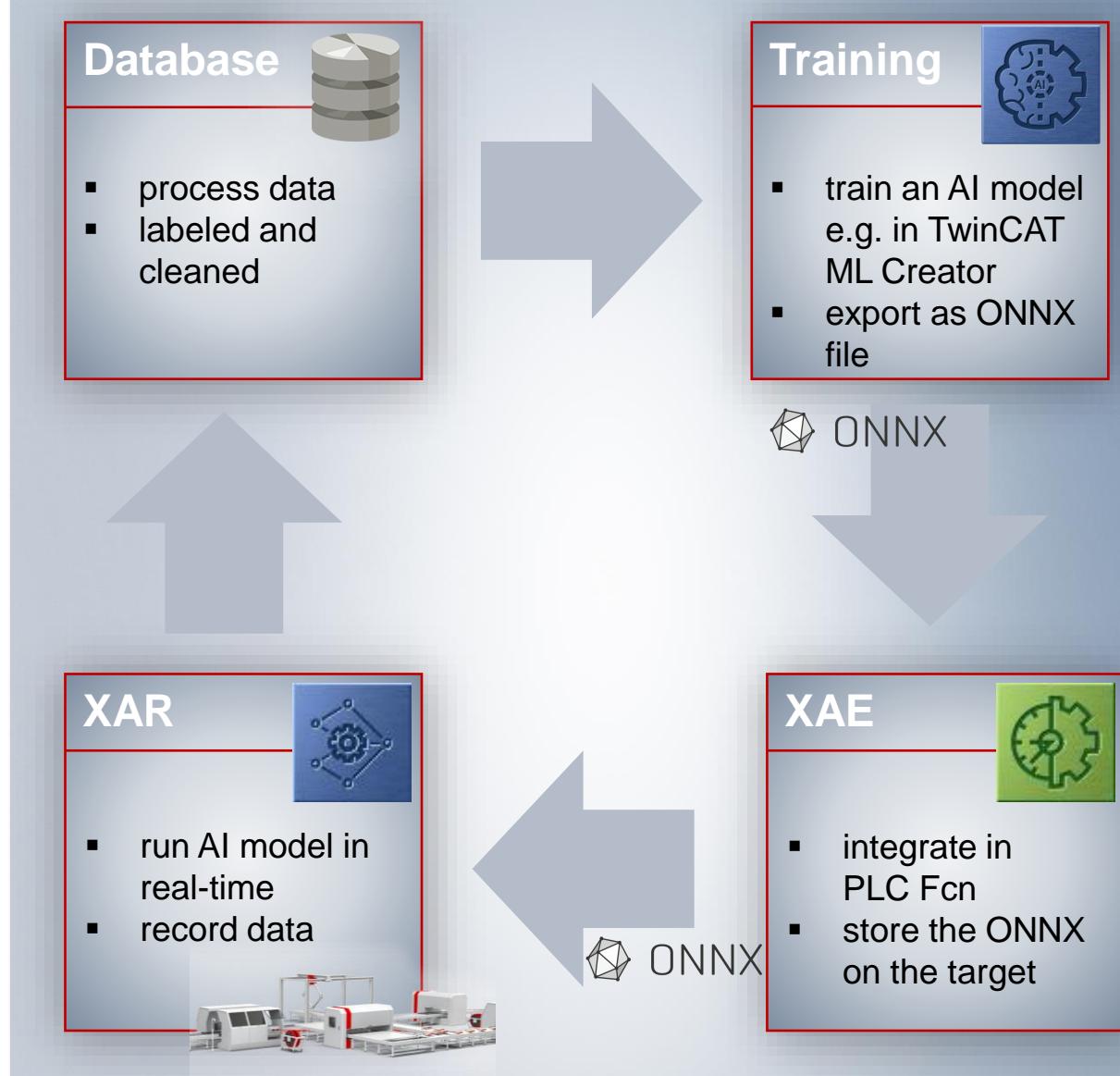
Execution details

- CPU and GPU execution
- near real-time execution in a separate user-mode process

Interface

```
bDone := fbModel.Predict(  
    pDataIn := ADR(ModelIn),  
    nDataInpDim := SIZEOF(ModelIn),  
    pDataOut := ADR(ModelOut),  
    nDataOutDim :=  
    SIZEOF(ModelOut),...)
```

Supported models
▪ all models



Flexible integration strategies

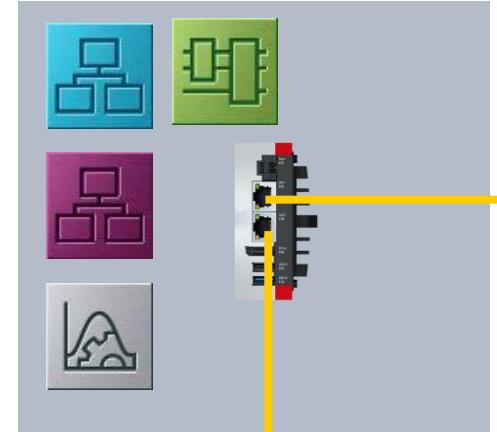
Fully integrated vs. modular add-on

BECKHOFF

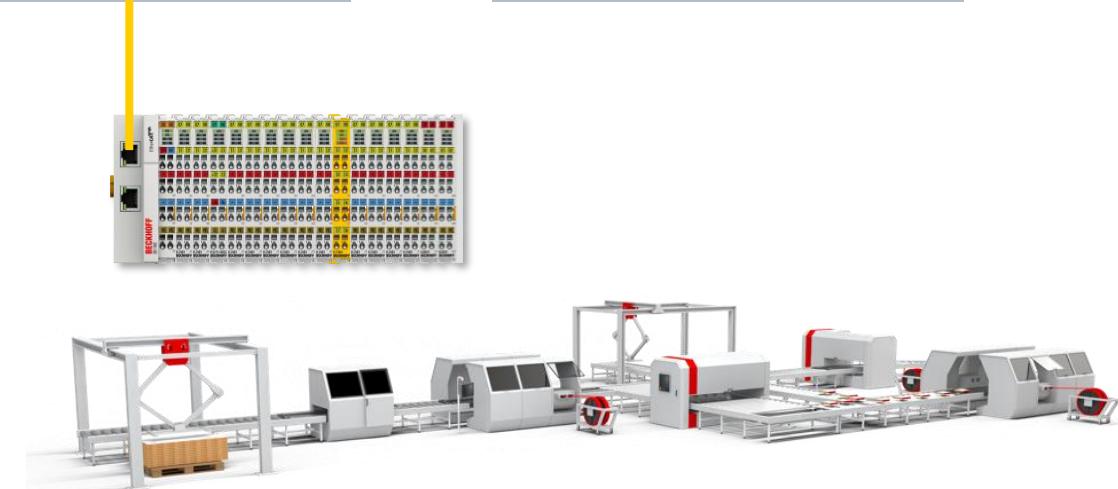
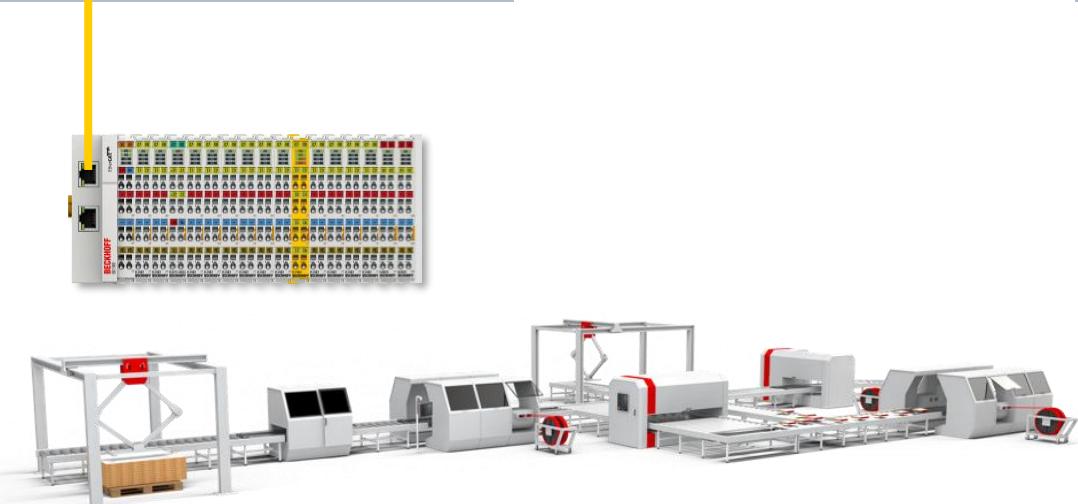
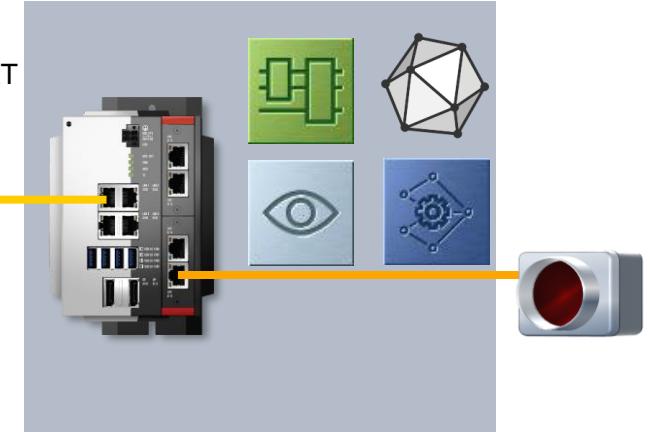
Control and AI system



Control system



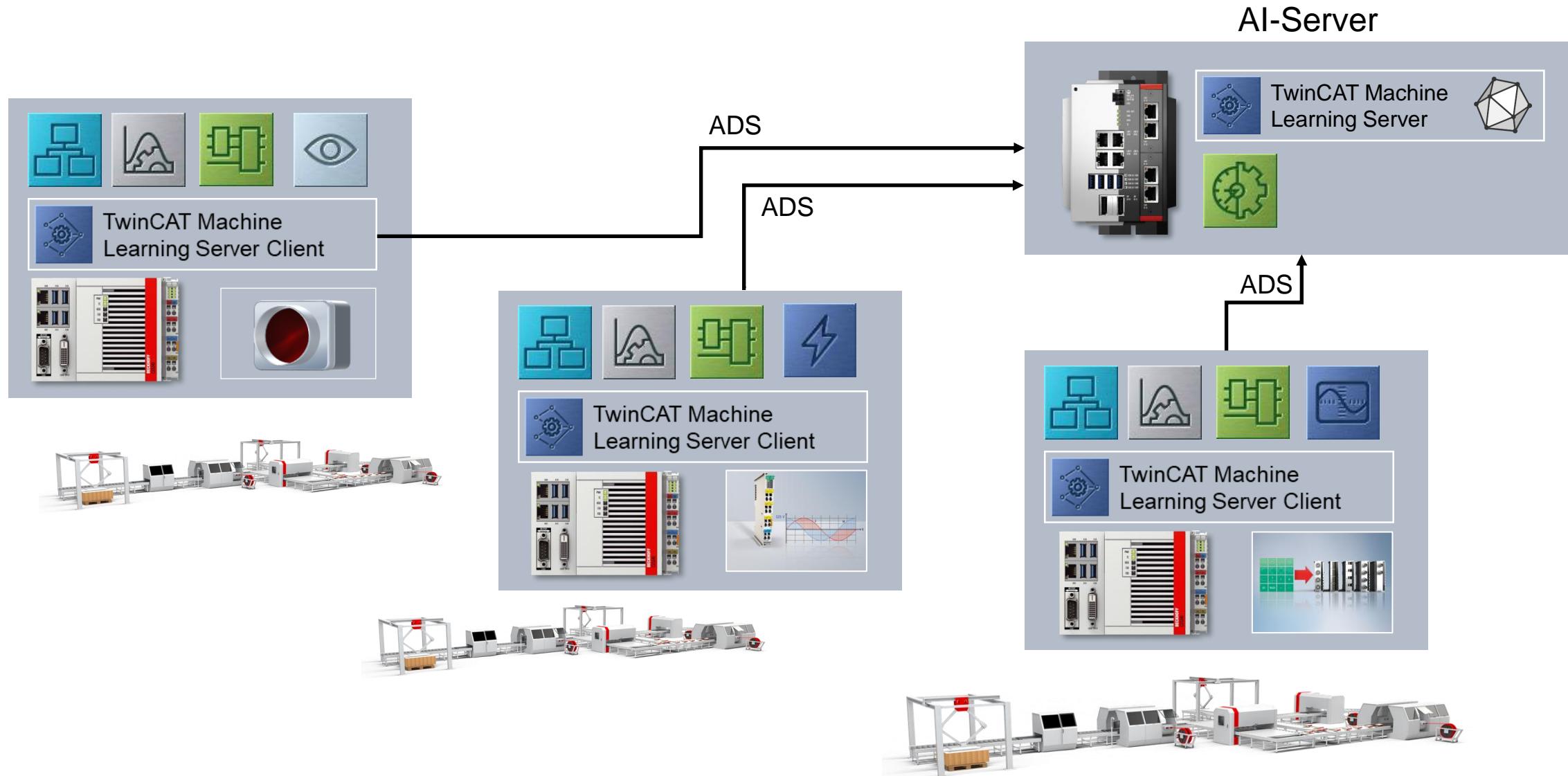
AI add-on system



Flexible integration strategies

Multiple clients calling multiple AI models on a central server instance

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CoAgent

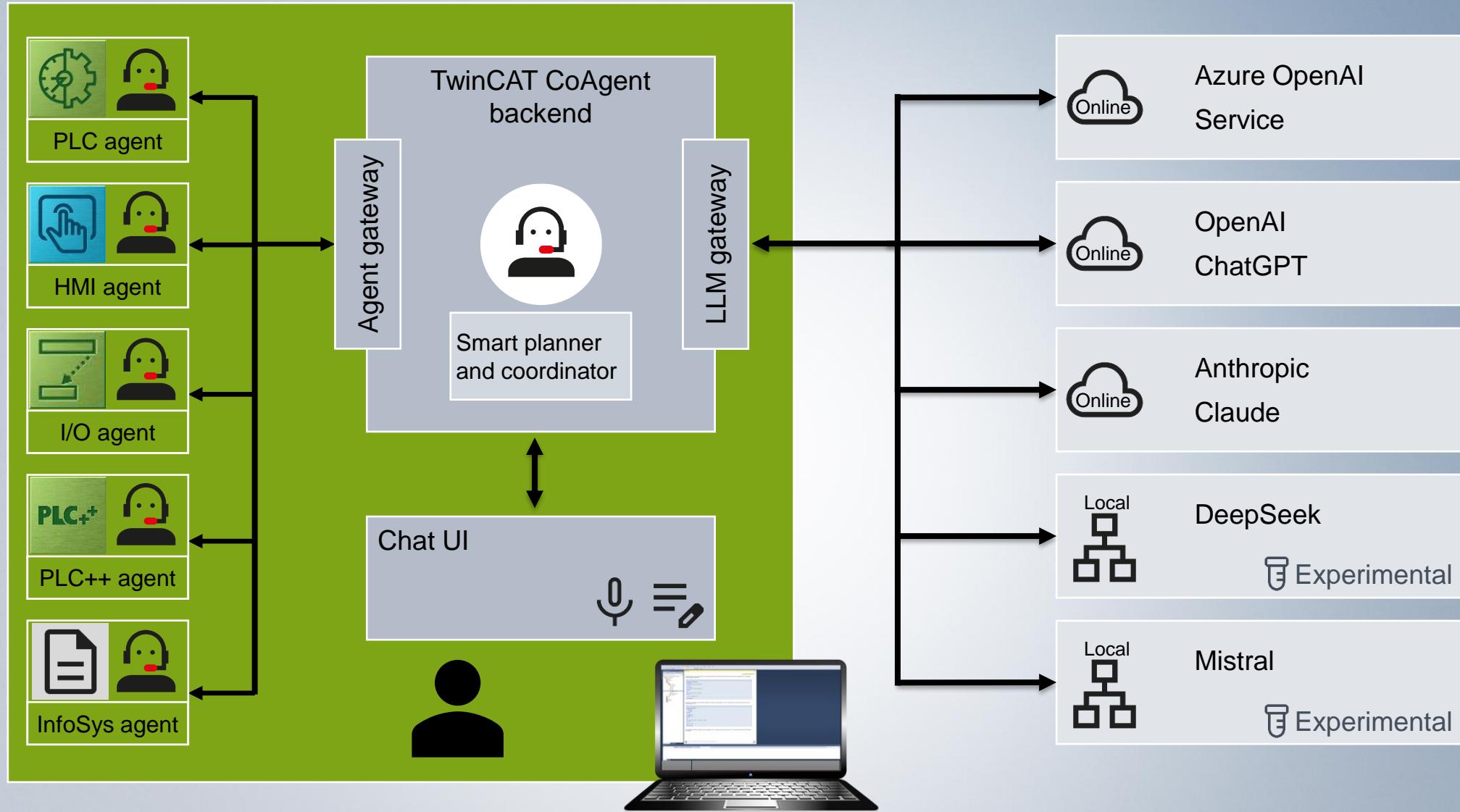


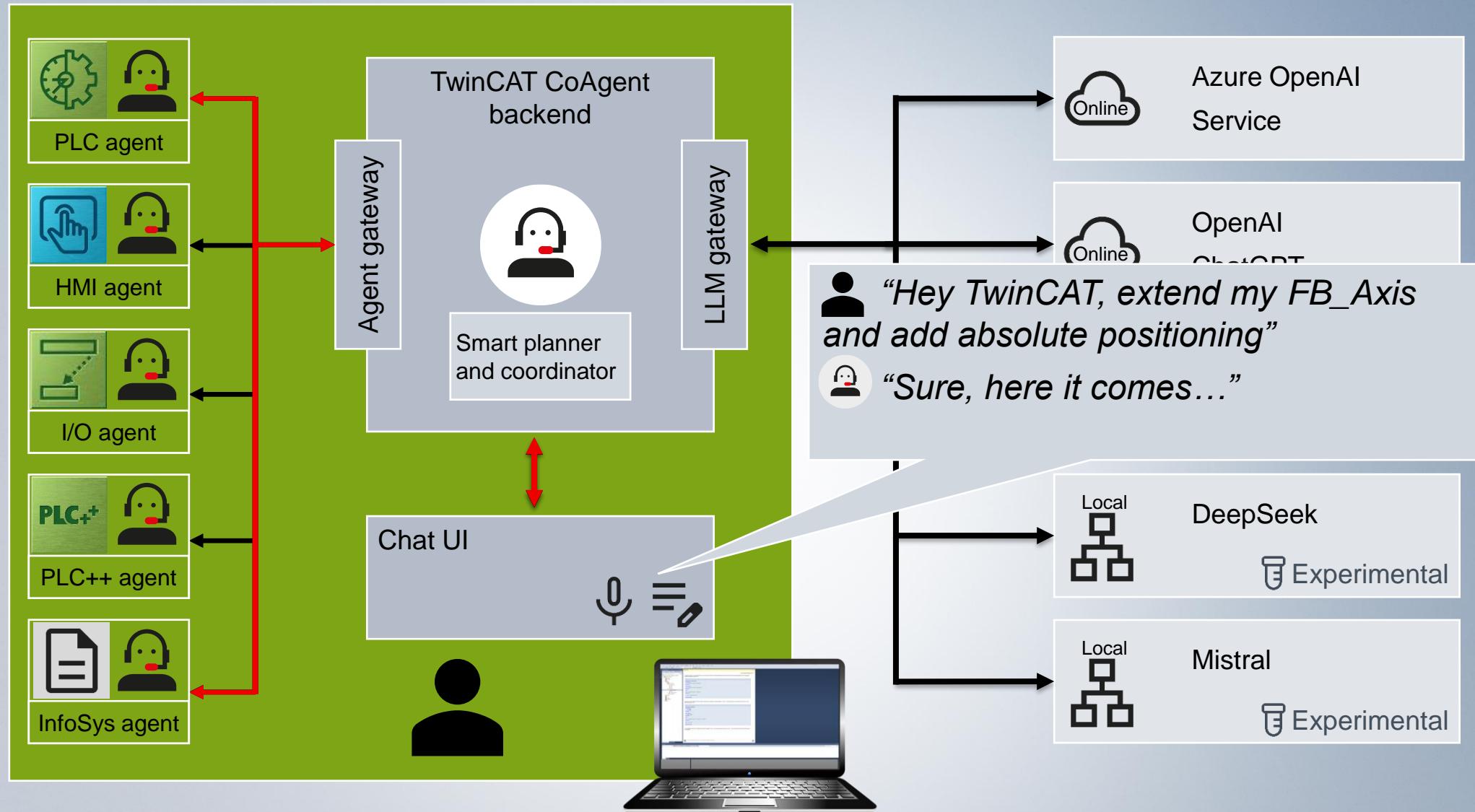
TwinCAT CoAgent for automation engineering

- smart AI-based agents to
 - shorten development cycles
 - improve software quality
 - increase productivity

TwinCAT CoAgent for automation runtime

- smart AI-based agent to
 - shorten downtimes
 - increase productivity
 - translate from machine to human





File Edit View Git Project Build Visualization Debug TwinCAT TwinCAT HMI TwinSAFE PLC Tools Window Help Search TwinCAT CoAgent Sample GitHub Copilot ADMIN

Release TwinCAT RT (x64) Google Chrome Plc1 1

Solution Explorer

Search Solution Explorer (Ctrl+U)

TcHmiProject

- Twincat CoAgent Sample
 - SYSTEM
 - MOTION
 - NC-Task 1 SAF
 - PLC
 - Plc1
 - Plc1 Project
 - References
 - DUTs
 - Generated
 - GVs
 - HMI
 - POUs
 - Templates
 - Complete
 - Guidelines
 - FB_Axis (FB)
 - Enable
 - Halt
 - MoveBw
 - MoveFw
 - Reset
 - State_Enable
 - State_HaltDone
 - State_ResetDone
 - Stop
 - Velocity
 - FB_RunningLight_g (FB)
 - Optimize
 - VISUS
 - PlcTask (PlcTask)
 - Prompts.txt
 - Plc1.tmc
 - Plc1 Instance
 - SAFETY
 - C++
 - VISION
 - ANALYTICS
 - I/O

TwinCAT CoAgent

Name: chat_6 Model: anthropic/clause-3-7-sonnet-20250219 Agent: PLC Tools: 3

chat_1
chat_2
chat_3
chat_4
chat_5
chat_6

I'm your personal assistant for TwinCAT. Feel free to ask me anything by typing. Use /use or @ to give me additional information about your project

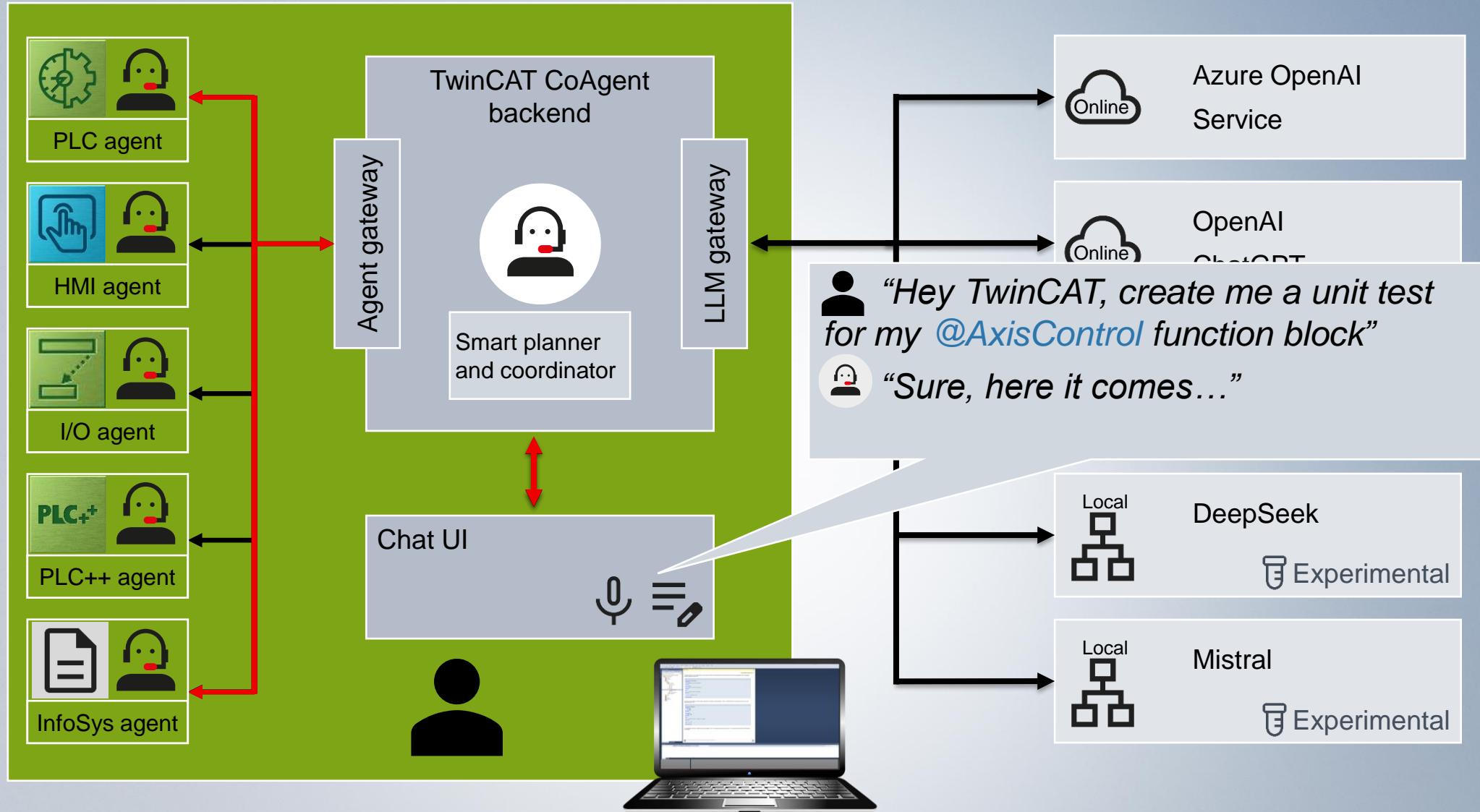
AI can make mistakes. Please double-check responses.

Solution Explorer Team Explorer Error List Output

Ready Add to Source Control Select Repository

TwinCAT CoAgent | Smart agents for automation engineering

BECKHOFF



File Edit View Git Project Build Visualization Debug TwinCAT TwinCAT HMI TwinSAFE PLC Tools Window Help Search TwinCAT CoAgent Sample GitHub Copilot ADMIN

Build 4026.14 (Loaded) TwinCAT CoAgent Samp <Local> Plc1 1

Solution Explorer

Search Solution Explorer (Ctrl+U)

Solution 'TwinCAT CoAgent Sample' (1 of 1 project)

- TwInCAT CoAgent Sample
 - SYSTEM
 - MOTION
 - NC-Task 1 SAF
 - PLC
 - Plc1
 - Plc1 Project
 - References
 - DUTs
 - Generated
 - GVLs
 - HMI
 - POUs
 - Templates
 - Complete
 - Guidelines
 - FB_Axis (FB)
 - Enable
 - Halt
 - MoveAbsolute
 - MoveBw
 - MoveFw
 - Reset
 - State_Enable
 - State_HaltDone
 - State_ResetDone
 - Stop
 - Velocity
 - FB_RunningLight_g (FB)
 - Optimize
 - VISUS
 - PlcTask (PlcTask)
 - Prompts.txt
 - Plc1.tmc
 - Plc1 Instance
 - SAFETY
 - C++
 - VISION
 - ANALYTICS
 - I/O

FB_Axis.MoveAbsolute

```
1 METHOD MoveAbsolute
2   VAR_INPUT
3     bExecute      : BOOL;           // Execute the absolute movement
4     fPosition     : LREAL;          // Target absolute position
5     fVelocityAbs : LREAL;          // Velocity for the absolute movement
6   END_VAR
7   VAR_OUTPUT
8     bDone         : BOOL;          // Movement completed
9     bCommandAborted: BOOL;        // Command was aborted
10  END_VAR
11
12 // Call the MC_MoveAbsolute function block with the provided parameters
13 fbMcMoveAbs(
14   Execute := bExecute,
15   Position := fPosition,
16   Velocity := fVelocityAbs,
17   Axis := AxisRef
18 );
19
20 // Update status and error information
21 IF fbMcMoveAbs.Error THEN
22   bError := TRUE;
23   nErrorID := fbMcMoveAbs.ErrorID;
24 END_IF
25
26 // Update output parameters
27 bDone := fbMcMoveAbs.Done;
28 bCommandAborted := fbMcMoveAbs.CommandAborted;
29
30 // Update the movement status
31 AxisRef.ReadStatus();
32 bMoves := AxisRef.Status.Moving;
```

100 %

TwinCAT CoAgent

Name: chat_7 Model: anthropic/clause-3-7-sonnet-20250219 Agent: PLC Tools: 3

 - chat_1
 - chat_2
 - chat_3
 - chat_4
 - chat_5
 - chat_6
 - chat_7

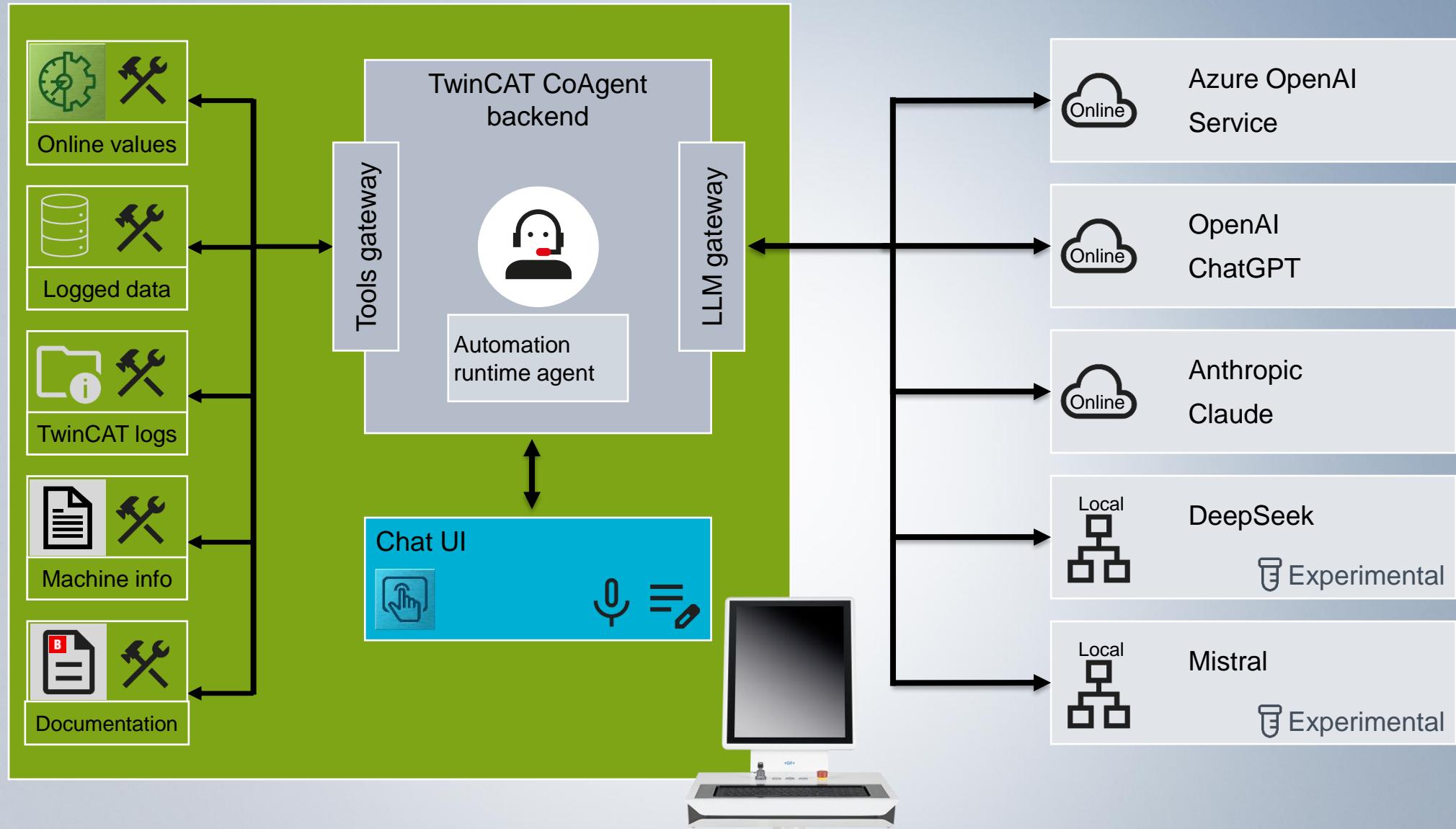
I'm your personal assistant for TwinCAT. Feel free to ask me anything by typing. Use /use or @ to give me additional information about your project

+

AI can make mistakes. Please double-check responses.

Solution Explorer Team Explorer Error List Output

Ready Add to Source Control Select Repository



Overview

Overview

| | | |
|---------|------------------|--------|
| Station | Position Z | 179 |
| Milling | Spindle Rotation | 2000 |
| | Total operations | 474308 |

Station

Quality Check



Station

Monitoring



Last production cycle time

10.46s

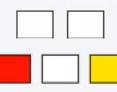
Station

Detection



Station

Storage



< Back

Overview

Orders

Vision

Storage

Trending

Settings

CoAgent



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